

## Characterisation of the flow regimes of arbitrary manoeuvre in absolute and relative frames

I. Gledhill<sup>1</sup> and J. Nordström<sup>2</sup>

<sup>1</sup>Aeronautical Systems Competency Area,  
Defence, Peace, Safety and Security Operational Unit, CSIR

<sup>2</sup> Dept of Mathematics, U Linköping,  
Linköping, Sweden



## Outline

Warning: this is a theory paper

- Context
- Background
- Some of the CFD background
- Computational background
- Theoretical background
- In the relative frame, in order to investigate relative size of terms,
- Continuity equation
- Momentum equation
- Energy equation

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## Outline II

- Dimensionless constants
- A question: longitudinal independence in rockets?
- Some illustrations
- Conclusions
- Further work

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## Context

- Engineering tools useless without...
- Engineering judgment which is based on...
- Understanding

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## Objectives: overall

- A formal framework for arbitrary manoeuvre
- CFD modelling of arbitrary manoeuvre
- Characterise dynamic loads in arbitrary manoeuvre

### Objectives: specific

- Include acceleration terms  $\ddot{r}$  and  $\dot{\omega}$  in relative (body) frame formulation
- Include energy equation
- Find dimensionless numbers that are useful
- And thereby build the next step in the programme

Note: can only characterise linear behaviour in this way; nonlinear behaviour needs models

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## Background

- Batchelor, Greenspan, Landau and Lifshitz
- Directed largely at understanding atmospheric flows and waves
- Axial turbines
- Rothalpy and constant  $\omega$  behaviour
- Flight dynamics
- The aims: bring this old news into CFD of arbitrary manoeuvres

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### CFD background

- Moving grids:
  - Chimera overset grids
  - Arbitrary Lagrangian Eulerian, ALE
  - Constant rotation  $\omega$ : turbines and compressors
  - Small perturbations: aeroelasticity
  - Relative frame terms:
    - Roohani and Skews 2007...2011
- In the inertial frame:
  - Inoue *et al.*

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### Theory Background to present work

- Transformation between frames moving with constant relative velocity is trivial: Galilean
  - Transformation between frames with relative acceleration is subject of present programme
- Löfgren
  - General formulation of transforms in 4-space between inertial and relative frames
  - Invariants in transformation
- Forsberg
  - Löfgren's formulation to simpler formulation
  - Numerical implications of inertial and relative frames
  - Stability and convergence in inertial and relative frames
- Forsberg *et al.* 2009
  - Implementation, validation and test cases

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### The parameters

**$\Sigma$  inertial frame: absolute**

- Position vector of fluid element  $\underline{x}$
- Fluid velocity  $\underline{v} = \dot{\underline{x}}$
- Position of  $O'$   $\underline{r}$
- Velocity of  $O'$   $\underline{u} = \dot{\underline{r}}$
- Rotation vector of  $\Sigma'$  relative to  $\Sigma$   $\underline{\omega}$
- Rotational transform  $\underline{\tilde{x}} = \underline{r} + \underline{U} \cdot \underline{x}$

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### Vectors and transforms

**$\Sigma$  inertial frame: absolute**       **$\Sigma'$  body frame: relative**

- Position vector of fluid element  $\underline{x}$        $\underline{\tilde{x}}$
- Fluid velocity  $\underline{v} = \dot{\underline{x}}$        $\underline{v} - \underline{\dot{\tilde{x}}}$
- Position of  $O'$   $\underline{r}$        $\underline{r}$
- Velocity of  $O'$   $\underline{u} = \dot{\underline{r}}$        $\underline{u} = \dot{\underline{r}}$
- transform  $\underline{\tilde{x}} = \underline{r} + \underline{U} \cdot \underline{x}$   
 $\frac{\partial \underline{U}}{\partial t} = \underline{U} \left( \frac{\partial}{\partial t} + \underline{\omega} \times \right)$   
 $\underline{U}^t = \underline{U}^{-1}$

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### Vectors interpreted in the other frame

**Seen in  $\Sigma$  inertial frame: absolute**      **Seen in  $\Sigma'$  body frame: relative**

- vector  $\underline{a}$  as seen in  $\Sigma'$  is interpreted as  $\underline{\tilde{a}}$
- $\underline{x}$  as seen in  $\Sigma'$  is interpreted as  $\underline{\tilde{x}}$
- $\underline{\tilde{a}}$  as seen in  $\Sigma$  is interpreted as  $\underline{a}$
- $\underline{\tilde{x}}$  as seen in  $\Sigma$  is interpreted as  $\underline{x}$

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### Gravity vector interpreted in the other frame

**Seen in  $\Sigma$  inertial frame: absolute**      **Seen in  $\Sigma'$  body frame: relative**

- vector  $\underline{g}$  as seen in  $\Sigma'$  is interpreted as  $\underline{\tilde{g}}$

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### Scalars and intrinsic variables

**Absolute, inertial**


- $\rho$
- $p$
- $T$
- $\mu$
- $\nu$
- $\kappa$
- $\sigma$
- $\tau$

Stress tensors are dependant on velocity

**Relative: Conserved**

- $\rho$
- $p$
- $T$
- $\mu$
- $\nu$
- $\kappa$
- $\bar{\sigma}$
- $\bar{\tau}$

■ Is entropy S conserved?



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**Why is this notation so complex?**

- It distinguishes in detail the frame transforms
- And provides a general framework

**Why is it in the least important?**




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### The general equation in conservation form for a conserved intrinsic quality a

**Relative**

$$\frac{\partial}{\partial t}(\rho a) + \nabla \cdot (\rho a \underline{v} + \bar{F}_a) = Q_a$$




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### Mass conservation: the equation of continuity

**Relative**

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \underline{v}) = 0$$




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### Momentum conservation

**Relative**

$$\frac{\partial}{\partial t}(\rho \underline{v}) + \nabla \cdot (\rho \underline{v} \otimes \underline{v} + p \underline{I} - \bar{\tau}) = -\rho \dot{\underline{r}} - \rho \dot{\underline{\omega}} \times \underline{x} - 2\rho \underline{\omega} \times \underline{v} - \rho \dot{\underline{\omega}} \times (\underline{\omega} \times \underline{x}) + \rho \underline{g}$$



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### Energy conservation

**Relative**

$$E = e + \frac{\|\underline{v} + \underline{u}\|^2}{2}$$

$$a = E, \bar{F}_a = p \underline{v} - \bar{\tau} \cdot \underline{v} - \kappa \nabla T, Q_a = q_n + \underline{g} \cdot \underline{v}$$

$$\frac{\partial}{\partial t}(\rho E) + \nabla \cdot (\rho E \underline{v} + p \underline{v} - \bar{\tau} \cdot \underline{v} + p \underline{u} - \bar{\tau} \cdot \underline{u} - \kappa \nabla T) = q_n + \rho \underline{v} \cdot \underline{g} + \rho \dot{\underline{r}} \cdot \underline{g} + \rho \dot{\underline{\omega}} \times \underline{g}$$



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### Generalised rothalpy $E^*$

**Relative**


$$E^* = e + \frac{\|\underline{v}\|^2}{2} - \frac{\|\underline{u}\|^2}{2}$$

$$\frac{\partial}{\partial t}(\rho E^*) + \nabla \cdot (\rho E^* \underline{v} + p \underline{v} - \kappa \nabla T)$$

$$= q_H + \rho \tilde{r} \cdot \tilde{r} + \rho \tilde{r} \cdot \dot{\tilde{\omega}} \times \underline{x}$$

$$+ \rho \tilde{r} \cdot \dot{\tilde{\omega}} \times \underline{x} + \rho \dot{\tilde{\omega}} \times \underline{x} \cdot \dot{\tilde{\omega}} \times \underline{x}$$

$$+ \rho \underline{v} \cdot \tilde{r} + \rho \underline{v} \cdot \dot{\tilde{\omega}} \times \underline{x}$$

$$+ \rho \underline{v} \cdot \tilde{g} + \rho \tilde{r} \cdot \tilde{g} + \rho \dot{\tilde{\omega}} \cdot \tilde{g}$$



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### 1. First objective achieved...

- Write out the equations including  $\underline{g}$  and Viscous effects;
- And write out the energy equation in the relative frame.

**Why?**

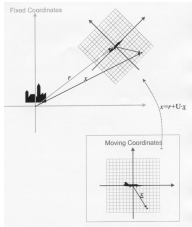

- Now we can look at physical effects.



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### 2. Next: find useful dimensionless constants for the momentum equation

- Several assumptions and notes:
  - First: comparison to convective effects
  - Only linear effects are identified this way
  - For the present, single-scale problems are written; but most  $r$  scales will differ from  $x$  scales
  - FYSA, Therefore, some gross simplifications

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### Momentum equation: typical scales

$$v = U v_1,$$

$$x = L x_1, \nabla = L^{-1} \nabla_1,$$

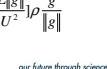
$$\omega = \Omega \omega_1, t = \Omega^{-1} t_1,$$

$$p = p_1, \rho_1 = \rho, \rho_1 = \rho, \tau = \nu \tau_1,$$

$$r = r_1,$$


$$\frac{\partial}{\partial t}(\rho \underline{v}) + \nabla \cdot (\rho \underline{v} \otimes \underline{v} + p I - \tau) = -\rho \tilde{r} - \rho \dot{\tilde{\omega}} \times \underline{x} - 2\rho \dot{\tilde{\omega}} \times \underline{v} - \rho \dot{\tilde{\omega}} \times (\dot{\tilde{\omega}} \times \underline{x}) + \rho \tilde{g}$$

$$\left[\frac{L}{tU}\right] \frac{\partial}{\partial t}(\rho \underline{v}) + \nabla \cdot (\rho \underline{v} \otimes \underline{v}) + \left[\frac{p}{\rho U^2}\right] \nabla \cdot p I - \left[\frac{\nu L}{U}\right] \nabla \cdot \tau$$

$$= -\left[\frac{L \dot{\tilde{\omega}}}{U^2}\right] \rho \tilde{r} - \left[\frac{L^2 \dot{\tilde{\omega}}}{U^2}\right] \rho \dot{\tilde{\omega}} \times \underline{x} - \left[2 \frac{L \Omega}{U}\right] \rho \dot{\tilde{\omega}} \times \underline{v} - \left[\frac{L^2 \Omega^2}{U^2}\right] \rho \dot{\tilde{\omega}} \times (\dot{\tilde{\omega}} \times \underline{x}) + \left[\frac{L \|\tilde{g}\|}{U^2}\right] \rho \frac{\tilde{g}}{\|\tilde{g}\|}$$


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- The formal structure underlying the simulations of Roohani and Skews 2007...

$$\frac{\partial}{\partial t}(\rho \underline{v}) + \nabla \cdot (\rho \underline{v} \otimes \underline{v} + p I - \tau) = -\rho \tilde{r} - \rho \dot{\tilde{\omega}} \times \underline{x} - 2\rho \dot{\tilde{\omega}} \times \underline{v} - \rho \dot{\tilde{\omega}} \times (\dot{\tilde{\omega}} \times \underline{x}) + \rho \tilde{g}$$



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### Extract meaning from models, term by term Strouhal

$$\left[\frac{L}{tU}\right] \frac{\partial}{\partial t}(\rho \underline{v}) + \nabla \cdot (\rho \underline{v} \otimes \underline{v}) + \left[\frac{p}{\rho U^2}\right] \nabla \cdot p I - \left[\frac{\nu L}{U}\right] \nabla \cdot \tau$$

$$= -\left[\frac{L \dot{\tilde{\omega}}}{U^2}\right] \rho \tilde{r} - \left[\frac{L^2 \dot{\tilde{\omega}}}{U^2}\right] \rho \dot{\tilde{\omega}} \times \underline{x} - \left[2 \frac{L \Omega}{U}\right] \rho \dot{\tilde{\omega}} \times \underline{v} - \left[\frac{L^2 \Omega^2}{U^2}\right] \rho \dot{\tilde{\omega}} \times (\dot{\tilde{\omega}} \times \underline{x}) + \left[\frac{L \|\tilde{g}\|}{U^2}\right] \rho \frac{\tilde{g}}{\|\tilde{g}\|}$$

- Strouhal number: typical temporal behaviour

$$St^{-1} = \frac{L}{tU}$$



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### Euler

$$\left[\frac{L}{tU}\right] \frac{\partial}{\partial t} (\rho \underline{v}) + \nabla \cdot (\rho \underline{v} \otimes \underline{v}) + \left[\frac{p}{\rho U^2}\right] \nabla \cdot pI - \left[\frac{VL}{U}\right] \nabla \cdot \underline{\tau}$$

$$= -\left[\frac{L\dot{\Gamma}}{U^2}\right] \rho \dot{\underline{r}} - \left[\frac{L^2\dot{\Omega}}{U^2}\right] \rho \dot{\underline{\omega}} \times \underline{x} - \left[2\frac{L\Omega}{U}\right] \rho \underline{\omega} \times \underline{v} - \left[\frac{L^2\Omega^2}{U^2}\right] \rho \underline{\omega} \times (\underline{\omega} \times \underline{x}) + \left[\frac{L\|g\|}{U^2}\right] \rho \frac{\underline{g}}{\|g\|}$$

- Euler number

$$Eu^{-1} = \frac{p}{\rho U^2}$$



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### Reynolds: translational viscous effects

$$\left[\frac{L}{tU}\right] \frac{\partial}{\partial t} (\rho \underline{v}) + \nabla \cdot (\rho \underline{v} \otimes \underline{v}) + \left[\frac{p}{\rho U^2}\right] \nabla \cdot pI - \left[\frac{VL}{U}\right] \nabla \cdot \underline{\tau}$$

$$= -\left[\frac{L\dot{\Gamma}}{U^2}\right] \rho \dot{\underline{r}} - \left[\frac{L^2\dot{\Omega}}{U^2}\right] \rho \dot{\underline{\omega}} \times \underline{x} - \left[2\frac{L\Omega}{U}\right] \rho \underline{\omega} \times \underline{v} - \left[\frac{L^2\Omega^2}{U^2}\right] \rho \underline{\omega} \times (\underline{\omega} \times \underline{x}) + \left[\frac{L\|g\|}{U^2}\right] \rho \frac{\underline{g}}{\|g\|}$$

- Reynolds number: typical viscous behaviour, different normalisation

$$Re^{-1} = \frac{\mu L}{\rho U}$$


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### Ekman: rotational viscous effects

$$\left[\frac{L}{tU}\right] \frac{\partial}{\partial t} (\rho \underline{v}) + \nabla \cdot (\rho \underline{v} \otimes \underline{v}) + \left[\frac{p}{\rho U^2}\right] \nabla \cdot pI - \left[\frac{VL}{U}\right] \nabla \cdot \underline{\tau}$$

$$= -\left[\frac{L\dot{\Gamma}}{U^2}\right] \rho \dot{\underline{r}} - \left[\frac{L^2\dot{\Omega}}{U^2}\right] \rho \dot{\underline{\omega}} \times \underline{x} - \left[2\frac{L\Omega}{U}\right] \rho \underline{\omega} \times \underline{v} - \left[\frac{L^2\Omega^2}{U^2}\right] \rho \underline{\omega} \times (\underline{\omega} \times \underline{x}) + \left[\frac{L\|g\|}{U^2}\right] \rho \frac{\underline{g}}{\|g\|}$$

- Ekman number: development of boundary layers and end-wall viscous phenomena in rotationally dominated flows

$$U = \Omega L$$

$$Ek^{-1} = \frac{\nu}{\Omega L^2}$$



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### Translational Acceleration of the frame

$$\left[\frac{L}{tU}\right] \frac{\partial}{\partial t} (\rho \underline{v}) + \nabla \cdot (\rho \underline{v} \otimes \underline{v}) + \left[\frac{p}{\rho U^2}\right] \nabla \cdot pI - \left[\frac{VL}{U}\right] \nabla \cdot \underline{\tau}$$

$$= -\left[\frac{L\dot{\Gamma}}{U^2}\right] \rho \dot{\underline{r}} - \left[\frac{L^2\dot{\Omega}}{U^2}\right] \rho \dot{\underline{\omega}} \times \underline{x} - \left[2\frac{L\Omega}{U}\right] \rho \underline{\omega} \times \underline{v} - \left[\frac{L^2\Omega^2}{U^2}\right] \rho \underline{\omega} \times (\underline{\omega} \times \underline{x}) + \left[\frac{L\|g\|}{U^2}\right] \rho \frac{\underline{g}}{\|g\|}$$

- Note the similarity to the gravitational term...

$$\frac{L\dot{\Gamma}}{U^2} \qquad \frac{Lg}{U^2}$$



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### Rotational Acceleration of the frame

$$\left[\frac{L}{tU}\right] \frac{\partial}{\partial t} (\rho \underline{v}) + \nabla \cdot (\rho \underline{v} \otimes \underline{v}) + \left[\frac{p}{\rho U^2}\right] \nabla \cdot pI - \left[\frac{VL}{U}\right] \nabla \cdot \underline{\tau}$$

$$= -\left[\frac{L\dot{\Gamma}}{U^2}\right] \rho \dot{\underline{r}} - \left[\frac{L^2\dot{\Omega}}{U^2}\right] \rho \dot{\underline{\omega}} \times \underline{x} - \left[2\frac{L\Omega}{U}\right] \rho \underline{\omega} \times \underline{v} - \left[\frac{L^2\Omega^2}{U^2}\right] \rho \underline{\omega} \times (\underline{\omega} \times \underline{x}) + \left[\frac{L\|g\|}{U^2}\right] \rho \frac{\underline{g}}{\|g\|}$$

- Angular acceleration

$$\frac{L^2\dot{\Omega}}{U^2}$$



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### Coriolis effects

$$\left[\frac{L}{tU}\right] \frac{\partial}{\partial t} (\rho \underline{v}) + \nabla \cdot (\rho \underline{v} \otimes \underline{v}) + \left[\frac{p}{\rho U^2}\right] \nabla \cdot pI - \left[\frac{VL}{U}\right] \nabla \cdot \underline{\tau}$$

$$= -\left[\frac{L\dot{\Gamma}}{U^2}\right] \rho \dot{\underline{r}} - \left[\frac{L^2\dot{\Omega}}{U^2}\right] \rho \dot{\underline{\omega}} \times \underline{x} - \left[2\frac{L\Omega}{U}\right] \rho \underline{\omega} \times \underline{v} - \left[\frac{L^2\Omega^2}{U^2}\right] \rho \underline{\omega} \times (\underline{\omega} \times \underline{x}) + \left[\frac{L\|g\|}{U^2}\right] \rho \frac{\underline{g}}{\|g\|}$$

- Rossby number:
- $Ro \ll 1$ , rotational effects dominate the flow; Taylor-Proudman columns in inviscid, isentropic, incompressible flow

$$Ro^{-1} = 2\frac{L\Omega}{U}$$


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### Centrifugal effects

$$\left[\frac{L}{U}\right] \frac{\partial}{\partial t} (\rho v) + \nabla \cdot (\rho v \otimes v) + \left[\frac{p}{\rho U^2}\right] \nabla \cdot pI - \left[\frac{V}{U}\right] \nabla \cdot \tau$$

$$= -\left[\frac{L^2}{U^2}\right] \rho \dot{\omega} - \left[\frac{L^2 \Omega}{U^2}\right] \rho \dot{\omega} \times \underline{x} - \left[2 \frac{L \Omega}{U}\right] \rho \bar{\omega} \times \underline{v} - \left[\frac{L^2 \Omega^2}{U^2}\right] \rho \bar{\omega} \times (\bar{\omega} \times \underline{x}) + \left[\frac{L \|g\|}{U^2}\right] \rho \frac{\bar{g}}{\|g\|}$$

$\frac{L^2 \Omega^2}{U^2}$   
 if  
 $U = R\Omega,$

- Centrifugal effects, e.g. wake curvature, are on scale  $\frac{R^2}{L^2}$




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### Gravitational effects

$$\left[\frac{L}{U}\right] \frac{\partial}{\partial t} (\rho v) + \nabla \cdot (\rho v \otimes v) + \left[\frac{p}{\rho U^2}\right] \nabla \cdot pI - \left[\frac{V}{U}\right] \nabla \cdot \tau$$

$$= -\left[\frac{L^2}{U^2}\right] \rho \dot{\omega} - \left[\frac{L^2 \Omega}{U^2}\right] \rho \dot{\omega} \times \underline{x} - \left[2 \frac{L \Omega}{U}\right] \rho \bar{\omega} \times \underline{v} - \left[\frac{L^2 \Omega^2}{U^2}\right] \rho \bar{\omega} \times (\bar{\omega} \times \underline{x}) + \left[\frac{L \|g\|}{U^2}\right] \rho \frac{\bar{g}}{\|g\|}$$

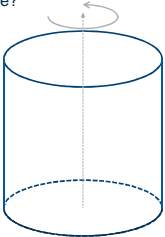

- buoyancy term in comparison to pressure effects in hydrostatics

$$\frac{Lg}{U^2} \frac{\phi}{\rho}$$


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### 3. A question: can Taylor columns exist in missile combustion chambers?

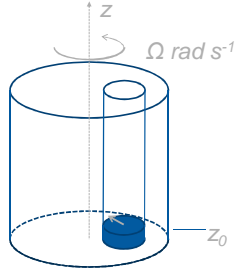

- When do rotational effects dominate?

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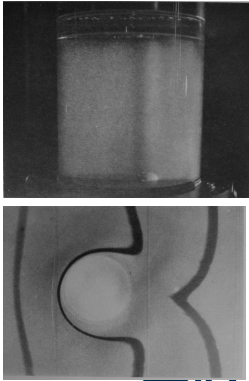

### Taylor-Proudman theorem

- Constant angular velocity  $\Omega$
- Rossby number  $Ro = U/2\Omega L$
- For  $Ro < 1$ , rotational effects dominate convection
- For **incompressible**, inviscid flow,
- $\partial/\partial z = 0$
- An obstacle A which is moved and generates streamlines at  $z_0$
- ...generates identical streamlines at all z

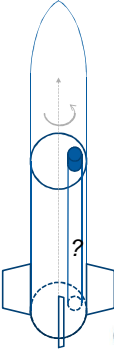

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- Accomplished by slight spin-up or spin-down
- Theory, Proudman 1916
- Experiment, Taylor 1917

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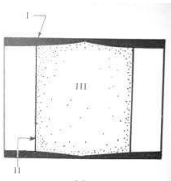
- Could Taylor columns exist in internal flow in missiles and rockets?
- What influence can be predicted on external flow?
- Progressive assumptions


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### Rockets or missiles considered as...

- Closed cylinders,
- Incompressible,
- Almost rigid rotation,
- With Rossby number  $Ro$  characterising rotational dominance
- Viscous effects can be characterised [Greenspan] by times scales related to the Ekman number:
- $t \sim 1$ , development of viscous boundary layers (I),
- $t \sim \Omega^{-1} Ek^{-1/2}$ , spin-up time (II, III),
- $t \sim \Omega^{-1} Ek^{1/2}$ , decay of residual viscous effects
- Take  $\nu$  for dry air for the present




[Greenspan] spin-up from rest:  
I Ekman boundary layer  
II front,  
III almost quiescent core



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### Typical values


- For rigid rotation,  $Ro \sim \frac{1}{2}$
- Will viscous effects dominate Taylor columns?
- Apache and Cajun sounding rockets
- Usselton and Carman ADC 1969
- $\Omega \sim 1.5$  to  $32 \text{ rads}^{-1}$ , radius  $59 \text{ mm}$
- Highly manoeuvrable missiles,
- Marquardt, Lawrence and Lawrence, AEDC, 1998
- $\Omega \sim 100 \text{ rads}^{-1}$ , radius  $r \sim 59 \text{ mm}$
- Unguided fin-stabilised artillery rockets, 122mm
- Khalil *et al.*, Egypt Armed Forces, 2009
- Muzzle  $\Omega \sim 100 \text{ rads}^{-1}$



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• For th


|                              | Low spin [Usselton and Carman 1969]    | Medium spin [Usselton and Carman 1969] | High spin [Khalil <i>et al.</i> 2009]  |
|------------------------------|--|--|--|
| Spin rate $\Omega$           | 1.5 rads <sup>-1</sup>                 | 32 rads <sup>-1</sup>                  | 100 rads <sup>-1</sup>   |
| Radius $r$                   | 59 mm                                  | 59 mm                                  | 61 mm  |
| $Ro$ , rigid                 | .5                                     | .5                                     | .5   |
| $Ek$                         | $70 \times 10^{-5}$                    | $3.4 \times 10^{-5}$                   | $1.1 \times 10^{-5}$   |
| Ekman layer time             | .67 s                                  | .03 s                                  | .01 s  |
| Spin up time                 | 24.9 s                                 | 5.4 s                                  | 3.1 s  |
| Residual viscous effect time | 930 s                                  | 930 s                                  | 930 s  |
| Comment                      | Taylor columns possible in this approx | Taylor columns possible in this approx | Ekman layer established fast, but Taylor columns possible (i.e., burn time is 1.8 s) |



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### Angular acceleration and translational acceleration

- Khalil *et al.* 2009
- Fin stabilised artillery rockets
- Measurements of translational acceleration, spin rate available
- $\dot{\omega} \sim 100 \text{ rads}^{-2}$ ,  $\omega \sim 100 \text{ rads}^{-1}$
- $\frac{L^2 \dot{\omega}}{U^2} \approx \frac{\dot{\omega}}{\Omega^2} \approx 0.01$
- Linear approximation indicates low angular acceleration effects...
- But we are aware of the vortex interactions through CFD
- $\dot{r} \sim 500 \text{ ms}^{-2}$  for thrust of 23600N,
- $\frac{L \dot{r}}{U^2} \sim 2.1$ , a significant factor even in these terms: translational acceleration likely to have significant effect




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### Translational acceleration

Roohani and Skews, 2007 and 2011

- Biconvex, NACA0012, NACA2412 and RAE2812 airfoils
- $\dot{r} = 1041 \text{ ms}^{-2}$
- For transonic cases,
- $\frac{L \dot{r}}{U^2} \sim 0.012$
- But very significant changes are experienced – and these are non-linear, due to shock position and shape
- Subsonic cases:  $U \sim 100 \text{ ms}^{-1}$
- $\frac{L \dot{r}}{U^2} \sim 0.1$ , and significant changes in linear range should be apparent




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### Conclusions

1. the energy equation is expressed in terms of translations and rotational acceleration,
2. the generalised enthalpy equation is similarly expressed,
3. but the meaning of these is still to be explored
4. dimensionless constants for momentum changes are re-derived,
5. But translational acceleration needs reconsideration in the light of numerical experiments,

And rotational indications by  $Ro$  and  $Ek$  are that Taylor columns in rockets need consideration in terms of heat transfer, boundary conditions and compressibility



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## Further work

- Compressibility
- Thermodynamics: is entropy conserved in frame transformation?
  - Express energy equation in terms of  $T$
  - Derive dimensionless numbers
- Taylor columns:
  - Compressibility
  - Boundary conditions
  - Heat transfer
- Shocks:
  - Do Rankine-Hugoniot relations transform?



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## Further work II

- Boundary conditions on accelerating walls
  - Boundary layer formation
- Turbulence
  - How do we deal with numerical turbulence models?
  - Is it appropriate to apply classic turbulence models even in the absolute frame?
- Perturbations
  - Rossby waves
  - Orr-Sommerfeld and transition



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¿questions?

